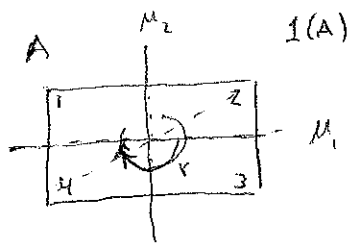


## Section 1.2 Dihedral Groups

Important class of groups: Symmetries of geometric objects

A symmetry or rigid motion of a geometric object  $A$  is a map  $M: A \rightarrow A$  that does not deform  $A$ .

Example Symmetries of a rectangle  $A$ .



$$1 \rightarrow 1 \\ 2 \rightarrow 2 \\ 3 \rightarrow 3 \\ 4 \rightarrow 4$$



$$1 \rightarrow 4 \\ 2 \rightarrow 3 \\ 3 \rightarrow 2 \\ 4 \rightarrow 1$$



$$1 \rightarrow 2 \\ 2 \rightarrow 1 \\ 3 \rightarrow 4 \\ 4 \rightarrow 3$$



$$1 \rightarrow 3 \\ 2 \rightarrow 4 \\ 3 \rightarrow 1 \\ 4 \rightarrow 2$$

|       | 1     | $M_1$ | $M_2$ | $r$   |
|-------|-------|-------|-------|-------|
| 1     | 1     | $M_1$ | $M_2$ | $r$   |
| $M_1$ | $M_1$ | 1     | $r$   | $M_2$ |
| $M_2$ | $M_2$ | $r$   | 1     | $M_1$ |
| $r$   | $r$   | $M_2$ | $M_1$ | 1     |

Under composition, these symmetries form a group.

Called the group of symmetries of  $A$ .

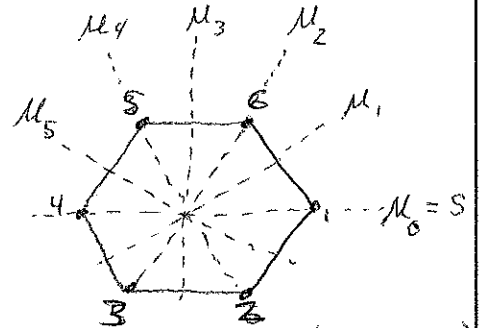
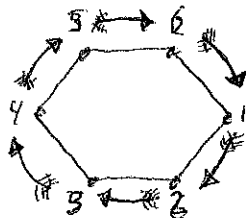
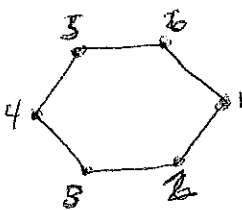
## Section 1.2

### The Dihedral Groups $D_{2n}$ - $D_2, D_4, D_6, D_8 \dots$ etc.

$D_{2n}$  = Group of symmetries of regular  $n$ -gon.

#### Example

$D_{12} = D_{2 \cdot 6}$  = Group of symmetries of hexagon.



$$r = \begin{pmatrix} \text{rotation} \\ \text{by } \frac{2\pi}{6} \end{pmatrix}$$

$$r^i = \underbrace{r \cdot r \cdot \dots \cdot r}_i = \begin{pmatrix} \text{rotation} \\ \text{by } \frac{2\pi \cdot i}{6} \end{pmatrix}$$

$$r^6 = 1$$

$$M_i = \begin{pmatrix} \text{reflection across} \\ \text{line at angle } \frac{\pi \cdot i}{6} \\ \text{with } s\text{-axis} \end{pmatrix}$$

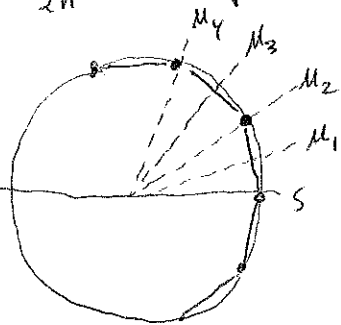
$$M_i^2 = 1$$

$$M_i^{-1} = M_i$$

$$D_{12} = \{ 1, r, r^2, r^3, r^4, r^5, s, M_1, M_2, M_3, M_4, M_5 \}$$

#### In General

$D_{2n}$  = Group of symmetries of regular  $n$ -gon.



$$r = \begin{pmatrix} \text{rotation by} \\ \frac{2\pi}{n} \end{pmatrix}$$

$$M_i = \begin{pmatrix} \text{reflection across} \\ \text{line at angle } \frac{\pi \cdot i}{n} \\ \text{with } s\text{-axis} \end{pmatrix}$$

$$D_{2n} = \{ 1, r, r^2, r^3, \dots, r^{n-1}, s, M_1, M_2, \dots, M_{n-1} \}$$

Note:  $|D_{2n}| = 2n$

But how does multiplication work out? e.g.  $M_j M_k = ?$

Key to answer: Work out  $S M_k$

$$S M_k = \begin{pmatrix} \text{rotation by} \\ 2\alpha + 2\beta = \\ 2(\alpha + \beta) = \\ 2\left(\frac{\pi}{n}k\right) = \frac{2\pi}{n}k \end{pmatrix} = r^k$$

$S M_k = r^k$

$$S M_k = r^k$$

$$M_k = S^{-1} r^k$$

$M_k = S r^k$

$$M_k^{-1} = r^{-k} S^{-k}$$

$M_k = r^{-k} S$

$M_k = S r^k$

$M_k^{-1} = r^{-k} S$

Update:

$$D_{2n} = \{ 1, r, r^2, \dots, r^{n-1}, s, M_1, M_2, \dots, M_{n-1} \}$$

$D_{2n} = \{ 1, r, r^2, \dots, r^{n-1}, s, sr, sr^2, \dots, sr^{n-1} \}$

Multiplication in  $D_{2n}$ :

$$(sr^k)(sr^l) = r^{-k} s s r^l = r^{-k} r^l = r^{l-k} \pmod{n}$$

$$r^k (sr^l) = (r^k s) r^l = s r^{-k} r^l = s r^{l-k} \pmod{n}$$

$$r^k r^l = r^{k+l}$$

From this you can work out the entire mult. table.

## Generators and Relations

$$D_{2n} = \{ 1, r, r^2, \dots, r^{n-1}, s, sr, sr^2, \dots, sr^{n-1} \}$$

Note Every element of  $D_{2n}$  is a product of  $r$ 's and  $s$ 's.  
We say  $r$  and  $s$  are generators of  $D_{2n}$ .

They obey the relations  $r^n = 1$ ,  $s^2 = 1$ ,  $rs = sr^{-1}$  and the entire multiplication structure can be worked out through these relations.

We write  $D_{2n} = \langle \underbrace{r, s}_{\text{generators}} \mid \underbrace{r^n = 1, s^2 = 1, rs = sr^{-1}}_{\text{relations}} \rangle$

Example  $\langle r \mid r^5 = 1 \rangle = \{ 1, r, r^2, r^3, r^4 \} \cong \mathbb{Z}/5\mathbb{Z}$ .

Example  $\langle a, b \mid ab = ba \rangle = \{ a^k b^l \mid k, l \in \mathbb{Z} \}$   
 $\cong \{ (a^k, b^l) \mid k, l \in \mathbb{Z} \}$   
 $\cong \mathbb{Z} \times \mathbb{Z}$ .

In general we can always describe a group as

$$G = \langle \underbrace{S}_{\text{set of generators}} \mid \underbrace{R_1, R_2, \dots, R_n}_{\text{relations}} \rangle$$

Exercise Describe the group  $G = \langle a, b \mid a^2 = 1, b^2 = 1 \rangle$

$$G = \{ 1, a, b, ab, ba, aba, bab, abab, baba, \dots \}$$

$$(abab)(bab) = abab^2ab = ab a^2 b = ab^2 = a$$

etc

$$(abab)^{-1} = baba$$